

## Question 3

### AC small-signal Buck Converter

#### Define unit:

$$\mu \equiv 10^{-6} \quad \text{m} \equiv 10^{-3} \quad \text{V} := 1 \quad \text{k}\Omega \equiv 10^3 \quad \Omega \equiv 1 \quad \text{k} \equiv 10^3 \quad \text{H}_Z \equiv 1 \quad \text{nF} \equiv 10^{-9} \quad \text{pF} \equiv 10^{-12}$$

$$\text{dB} \equiv 1 \quad \text{rad} \equiv 1 \quad \text{kHz} \equiv 10^3$$

#### Buck Parameters:

$$L := 35\mu \quad C := 440\mu \quad R_{\text{ESR}} := 25\text{m} \quad V_{\text{d}} := 18\text{V} \quad V_{\text{o}} := 12\text{V} \quad R := 6\Omega$$

$$f_{\text{s}} := 100\text{k} \quad V_{\text{m}} := 2\text{V} \quad V_{\text{ref}} := 2\text{V}$$

#### Compensator Specifications:

$$f_{\text{co}} := 10\text{k} \quad \omega_{\text{co}} := 2 \cdot \pi f_{\text{co}}$$

#### Pole-zero Locations:

$$\omega_{\text{zESR}} := \frac{1}{R_{\text{ESR}} \cdot C} \quad \omega_{\text{zESR}} = 9.091 \times 10^4 \quad f_{\text{zESR}} := \frac{\omega_{\text{zESR}}}{2\pi} \quad f_{\text{zESR}} = 14.469 \text{ kHz}$$

$$\omega_{\text{o}} := \frac{1}{\sqrt{L \cdot C}} \quad \omega_{\text{o}} = 8.058 \times 10^3 \quad f_{\text{o}} := \frac{\omega_{\text{o}}}{2\pi} \quad f_{\text{o}} = 1.283 \text{ kHz}$$

$$Q := \frac{R}{\omega_{\text{o}} \cdot L} \quad Q = 21.274 \quad g_{\text{od}} := V_{\text{d}}$$

#### Bode plot setting:

$$N := 1000 \quad r := 0..N - 1 \quad f_{\text{start}} := 100 \quad f_{\text{stop}} := 1000\text{k} \quad f_r := f_{\text{start}} \cdot \left( \frac{f_{\text{stop}}}{f_{\text{start}}} \right)^{\frac{r}{N-1}}$$

$$G_{\text{oc}}(s) := g_{\text{od}} \cdot \frac{\left( 1 + \frac{s}{\omega_{\text{zESR}}} \right)}{1 + \frac{s}{Q \cdot \omega_{\text{o}}} + \frac{s^2}{\omega_{\text{o}}^2}} \cdot \frac{1}{V_{\text{m}}}$$

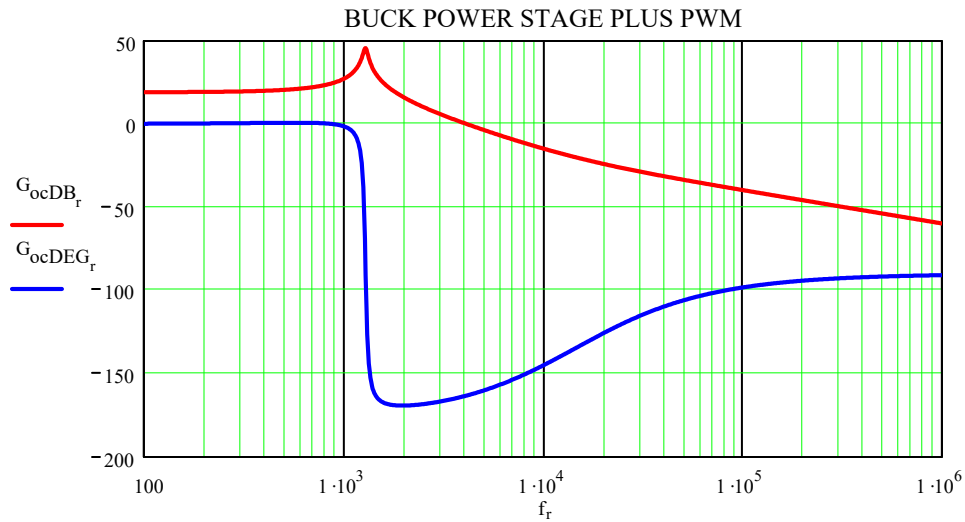
$$20 \log\left( \left| G_{\text{oc}}(j \cdot 2 \cdot \pi \cdot 16.666\text{k}) \right| \right) = -21.747 \quad \text{Aco}$$

$$\arg\left( G_{\text{oc}}(j \cdot 2 \cdot \pi \cdot 16.666\text{k}) \right) = -130.754 \text{ deg} \quad \text{Pco}$$

#### Define quantities for Bode plotting:

$$G_{\text{ocDB}_r} := 20 \cdot \log\left( \left| G_{\text{oc}}(j \cdot 2 \cdot \pi \cdot f_r) \right| \right)$$

$$G_{\text{ocDEG}_r} := \arg\left( G_{\text{oc}}(j \cdot 2 \cdot \pi \cdot f_r) \right) \cdot \frac{180}{\pi}$$



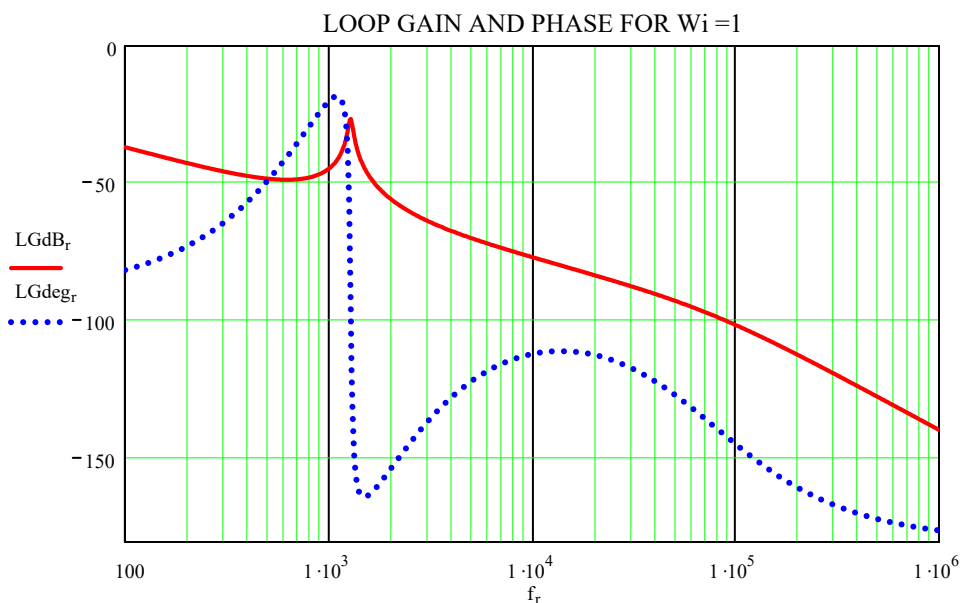
**Pole-zero Placement for compensator design:**

$$f_{z1} := f_o \quad f_{z2} := f_o \quad f_{p1} := f_{zESR} \quad f_{p2} := 0.75f_s \quad \omega_i := 1$$

$$C(s) := \frac{\omega_i \cdot \left(1 + \frac{s}{2 \cdot \pi \cdot f_{z1}}\right) \cdot \left(1 + \frac{s}{2 \cdot \pi \cdot f_{z2}}\right)}{s \cdot \left(1 + \frac{s}{2 \cdot \pi \cdot f_{p1}}\right) \cdot \left(1 + \frac{s}{2 \cdot \pi \cdot f_{p2}}\right)} \quad LG(s) := G_{oc}(s) \cdot C(s)$$

**Define quantities for Bode plot of Loop Gain LG:**

$$LGdeg_r := \arg(LG(j \cdot 2 \cdot \pi \cdot f_r)) \cdot \frac{180}{\pi} \quad LGdB_r := 20 \cdot \log(|LG(j \cdot 2 \cdot \pi \cdot f_r)|)$$



Evaluate LG at fco for gain and phase:

$$\text{LGdB} := 20 \cdot \log\left(\left|\text{LG}(j \cdot 2 \cdot \pi \cdot f_{\text{co}})\right|\right) \quad \text{LGdB} = -76.67 \quad 10^{\frac{-76.67}{20}} = 1.467 \times 10^{-4}$$

$$\text{LGph} := \arg\left(\text{LG}(j \cdot 2 \cdot \pi \cdot f_{\text{co}})\right) \cdot \frac{180}{\pi} \quad \text{LGph} = -111.86$$

Phase Margin:

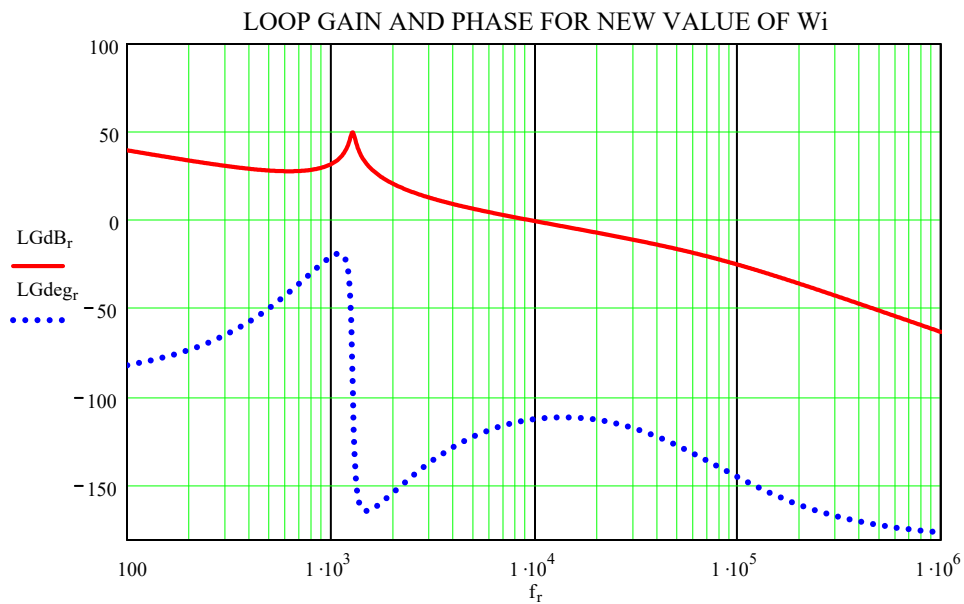
$$\text{PM} := 180 + \text{LGph} \quad \text{PM} = 68.14$$

The gain,  $\omega_i$ , required:

$$\omega_i := 10^{\frac{-\text{LGdB}}{20}} \quad \omega_i = 6.815 \times 10^3$$

Bode plot for new value for  $\omega_i$ :

$$\text{LGdB}_r := 20 \cdot \log\left(\left|\text{LG}(j \cdot 2 \cdot \pi \cdot f_r)\right|\right) - \text{LGdB}$$



**To find component values of error amplifier:**

Let  $R_3 := 10\text{k}\Omega$

$$C_3 := \frac{f_{z2}}{\omega_i \cdot R_3 \cdot f_{p2}} \quad C_3 = 250.908 \text{ pF}$$

$$C_2 := C_3 \cdot \left( \frac{f_{p2}}{f_{z2}} - 1 \right) \quad C_2 = 14.422 \text{ nF}$$

$$R_2 := \frac{1}{2 \cdot \pi \cdot f_{z2} \cdot C_2} \quad R_2 = 8.605 \text{ k}\Omega$$

$$R_1 := \frac{R_3}{\left( \frac{f_{p1}}{f_{z1}} - 1 \right)} \quad R_1 = 0.973 \text{ k}\Omega$$

$$C_1 := \frac{1}{2 \cdot \pi \cdot f_{p1} \cdot R_1} \quad C_1 = 11.31 \text{ nF}$$

$$R_{\text{bias}} := \frac{V_{\text{ref}}}{V_o - V_{\text{ref}}} \cdot R_3 \quad R_{\text{bias}} = 2 \text{ k}\Omega$$