

Test #2: Solution Version: MEI-19

Dummy unit: $\Omega \equiv 1$ $A \equiv 1$ $V \equiv 1$ $W \equiv 1$ $kW \equiv 1 \cdot 10^3 \cdot W$ $Hz \equiv 1$
 $Nm \equiv 1$ $rpm \equiv 1$

Q1: DC Machine - speed of the motor under full load condition

Under full load: $P_{Rated} := 10.0kW$ $E_{aRated} := 100V$ $V_t := 100V$ $R_a := 0.1\Omega$

$$I_{aFL} := \frac{P_{Rated}}{E_{aRated}} \quad I_{aFL} = 100 \text{ A}$$

$$E_{aFL} := V_t - I_{aFL} \cdot R_a \quad E_{aFL} = 90 \text{ V}$$

Under no load: Given: $E_a = 99V$ at No load $\omega_{NL} := 1000rpm$

Therefore, $E_{aNL} := 99V$

(a) R_f and rotational loss

3 marks

For $E_a := 99V$ $I_f := 0.95A$

$$R_f := \frac{V_t}{I_f} \quad R_f = 105.263 \Omega$$

$$I_a := \frac{V_t - E_a}{R_a} \quad I_a = 10$$

Rotational loss: $P_{loss} := E_a \cdot I_a$ $P_{loss} = 990 \text{ W}$

(b) With armature reaction, $\phi_{FL} = 0.935\phi_{NL}$ (6.5% reduction in flux due to armature reaction)

$$\frac{E_{aFL}}{E_{aNL}} = \frac{0.935 \cdot \omega_{FL}}{\omega_{NL}} \quad \text{Therefore,} \quad \omega_{FL} := \frac{E_{aFL}}{E_{aNL}} \cdot \frac{\omega_{NL}}{0.935} \quad \omega_{FL} = 972.29 \text{ rpm}$$

3 marks

(c) With armature reaction:

For differential compound motor,

$$I_{f_eff} = I_f - I_{f_AR} - \frac{N_{sr}}{N_f} \cdot I_t$$

$$I_{f_AR} := 0.15A$$

$$I_f := 0.95A \quad I_{f_eff} := I_f - I_{f_AR} \quad I_{f_eff} = 0.8A$$

$$\frac{\omega_C}{\omega_D} = \frac{E_C}{E_D}$$

$$\omega_C := 1000rpm$$

$$\omega_D := 1100rpm$$

$$E_D := E_{aFL}$$

$$E_D = 90V$$

$$E_C := \frac{\omega_C}{\omega_D} \cdot E_D$$

$$E_C = 81.818V$$

From the graph, when

$$E_C = 81.8V$$

$$I_f = 0.58A$$

(Point C)

$$I_{f_eff} = I_f - I_{f_AR} - \frac{N_{sr}}{N_f} \cdot I_t$$

$$I_{f_eff} := 0.58A$$

$$I_{f_AR} := 0.15$$

$$N_f := 800$$

$$I_t := I_{aFL} + I_f$$

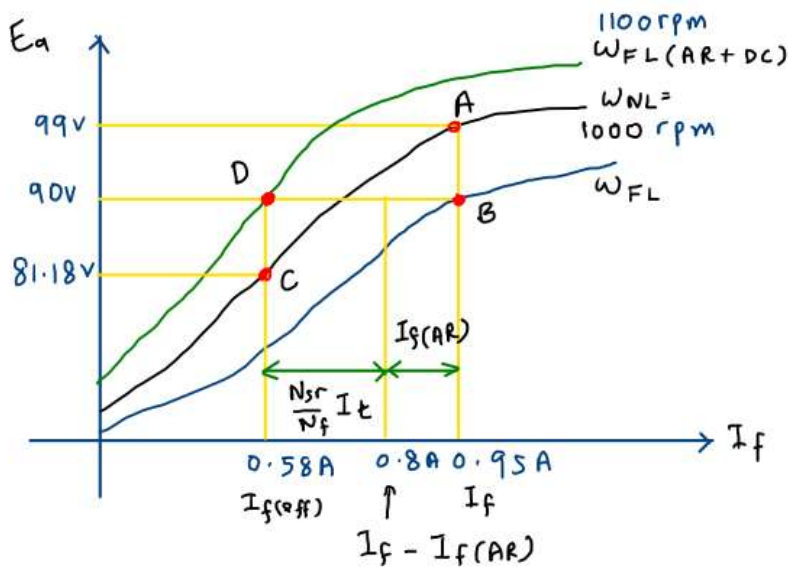
$$I_{aFL} = 100$$

$$I_f = 0.95$$

$$N_{sr} := (I_f - I_{f_AR} + I_{f_eff}) \cdot \frac{N_f}{I_t}$$

$$N_{sr} = 10.936$$

3 marks

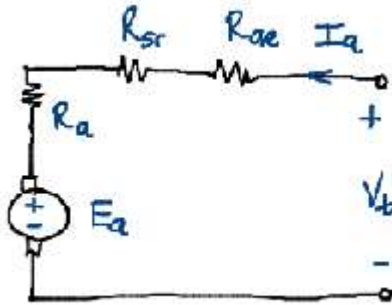


2 marks

Q2: DC Series Motor - Speed control of DC series motor by varying R_a .

$$V_t := 360\text{V} \quad R_a := 0.6\Omega \quad R_{sr} := 0.4\Omega$$

An Equivalent circuit of the series DC motor



(a) To determine key quantities at the operating point 1.

$$\text{Operation at point 1:} \quad \omega_{m1} := 600 \cdot \text{rpm} \quad I_{a1} := 33\text{A} \quad R_{ae1} := 0$$

Therefore,

$$E_{a1} := V_t - I_{a1} \cdot (R_a + R_{sr} + R_{ae1}) \quad E_{a1} = 327\text{V}$$

$$P_1 := E_{a1} \cdot I_{a1} \quad P_1 = 10.791\text{ kW}$$

$$T_1 := \frac{E_{a1} \cdot I_{a1}}{\frac{\omega_{m1}}{60} \cdot 2\pi} \quad T_1 = 171.744\text{ Nm}$$

2.5 marks

(b) To determine key quantities at the operating point 2.

$$\text{Operation at point 2:} \quad \omega_{m2} := 400 \cdot \text{rpm}$$

Since the load torque is proportional to square root of the motor speed,

$$T_2 := \left(\frac{\omega_{m2}}{\omega_{m1}} \right)^{2.1} \cdot T_1 \quad T_2 = 73.298$$

$$\text{To find } K_{sr}: \quad T_1 = K_{sr} \cdot I_{a1}^2 \quad K_{sr} := \frac{T_1}{I_{a1}^2} \quad K_{sr} = 0.158$$

$$I_{a2} := \sqrt{\frac{T_2}{K_{sr}}} \quad I_{a2} = 21.558\text{ A}$$

$$E_{a2} := K_{sr} \cdot I_{a2} \cdot \omega_{m2} \cdot \frac{2\pi}{60} \quad E_{a2} = 142.417\text{ V}$$

$$R_{ae2} := \frac{V_t - E_{a2}}{I_{a2}} - (R_a + R_{sr})$$

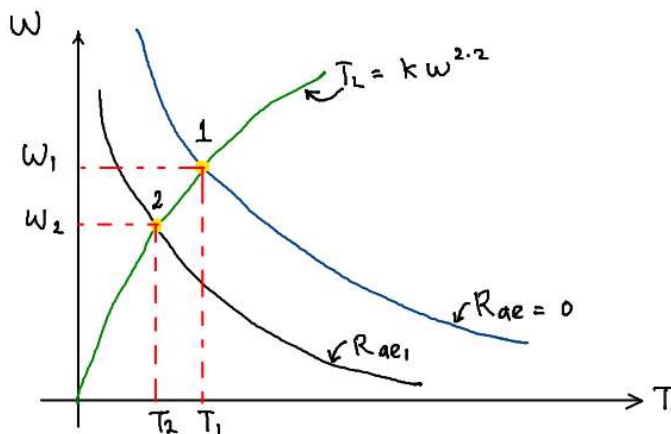
$$R_{ae2} = 9.093 \Omega$$

$$P_2 := E_{a2} \cdot I_{a2}$$

$$P_2 = 3.07 \text{ kW}$$

3 marks

(c) Speed-torque characteristics



1.5 marks

Q3: Induction Machine - power flow

$$V_L := 400 \text{ V}$$

$$I_L := 95 \text{ A}$$

$$P_{out} := 50 \text{ kW}$$

$$N_r := 580 \text{ rpm}$$

$$p := 10$$

$$f := 50 \text{ Hz}$$

Δ -connected

$$P_{rotat} := 1 \text{ kW}$$

$$\eta := 0.90$$

$$N_s := \frac{120 \cdot f}{p}$$

$$N_s = 600 \text{ rpm}$$

$$s := \frac{N_s - N_r}{N_s}$$

$$s = 0.033$$

i. $P_m := P_{out} + P_{rotat}$ $P_m = 51 \text{ kW}$

1 mark

ii. $P_{ag} := \frac{P_m}{(1-s)}$ $P_{ag} = 52.759 \text{ kW}$

1 mark

iii. $P_{rotor} := s \cdot P_{ag}$ $P_{rotor} = 1.759 \text{ kW}$

1 mark

iv. $P_{in} := \frac{P_{out}}{\eta}$ $P_{in} = 55.556 \text{ kW}$

1 mark

v. $P_{stator} := P_{in} - P_{ag}$ $P_{stator} = 2.797 \text{ kW}$

1 mark

vi. $P_{Losses} := P_{rotat} + P_{rotor} + P_{stator}$ $P_{Losses} = 5.556 \text{ kW}$

1 mark

$$P_{\text{losses}} := P_{\text{in}} - P_{\text{out}}$$

$$P_{\text{losses}} = 5.556 \text{ kW}$$

$$\text{vii. } P_{\text{in}} = \sqrt{3} \cdot V_L \cdot I_L \cdot \text{pf} \quad \text{pf} := \frac{P_{\text{in}}}{\sqrt{3} \cdot V_L \cdot I_L} \quad \text{pf} = 0.844 \quad \text{lagging}$$

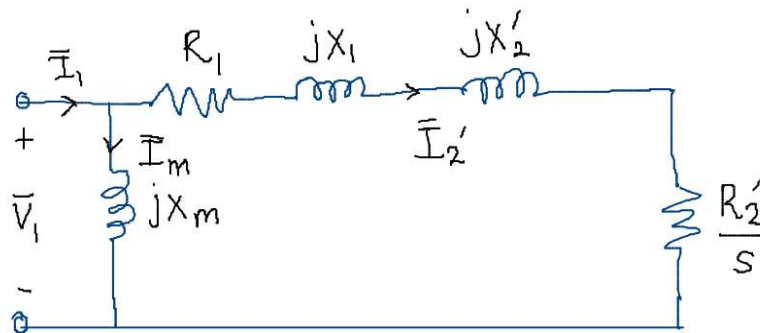
1 mark

Q4: Induction Machine - Equivalent Circuit Analysis

$$R_1 := 1.5 \Omega \quad R_2 := 0.65 \Omega \quad X_1 := 2 \Omega \quad X_2 := 1.2 \Omega \quad X_m := 50 \Omega$$

$$V_L := 400 \text{ V} \quad N_r := 720 \text{ rpm} \quad p := 8 \quad f := 50 \text{ Hz}$$

We use an approximate equivalent circuit. The calculation uses per phase quantities.



Connection Type:
Delta

$$V_1 := V_L \quad V_1 := 400 \text{ V} \quad N_s := \frac{120f}{p} \quad N_s = 750 \text{ rpm}$$

(a) Under starting condition, i.e. when $s := 1$; to find line current and power factor

	mag	phase
$I_2 := \frac{V_1}{R_1 + \frac{R_2}{s} + j \cdot (X_1 + X_2)}$	$ I_2 = 103.756 \text{ A}$	$\arg(I_2) = -56.104 \text{ deg}$

$I_m := \frac{V_1}{j \cdot X_m}$	$ I_m = 8 \text{ A}$	$\arg(I_m) = -90 \text{ deg}$
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$I_1 := I_2 + I_m$	$ I_1 = 110.487 \text{ A}$	$\arg(I_1) = -58.418 \text{ deg}$
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The power factor, $\text{pf} = \cos(\theta)$

$$\text{pf} := \cos(\arg(I_1)) \quad \text{pf} = 0.524 \quad \text{lagging}$$

3 marks

$$P_{\text{ag}} := (|I_2|)^2 \frac{R_2}{s} \quad P_{\text{ag}} = 6.997 \text{ kW}$$

$$\text{and } \omega_s := N_s \cdot \frac{2\pi}{60}$$

$$T := \frac{P_{\text{ag}}}{\omega_s} \quad T = 89.095 \text{ Nm} \quad \text{per phase}$$

(b) Under maximum torque condition, i.e. when $s = s_{Tmax}$; to find the maximum torque

$$s_{Tmax} := \frac{R_2}{\sqrt{R_1^2 + (X_1 + X_2)^2}} \quad s_{Tmax} = 0.184$$

$$s := s_{Tmax}$$

	mag	phase
$I_2 := \frac{V_1}{R_1 + \frac{R_2}{s} + j \cdot (X_1 + X_2)}$	$ I_2 = 67.057 \text{ A}$	$\arg(I_2) = -32.443 \text{ deg}$

$I_m := \frac{V_1}{j \cdot X_m}$	$ I_m = 8 \text{ A}$	$\arg(I_m) = -90 \text{ deg}$
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$I_1 := I_2 + I_m$	$ I_1 = 71.667 \text{ A}$	$\arg(I_1) = -37.848 \text{ deg}$
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$$P_{ag} := (|I_2|)^2 \frac{R_2}{s} \quad P_{ag} = 15.892 \text{ kW}$$

$$\text{and} \quad \omega_s := N_s \cdot \frac{2\pi}{60}$$

$$T := \frac{P_{ag}}{\omega_s} \quad T = 202.338 \text{ Nm} \quad \text{per phase}$$

3 marks

(c) Under full load, i.e. when $s := \frac{N_s - N_r}{N_s}$; to find efficiency at the full-load

$$s = 0.04$$

	mag	phase
$I_2 := \frac{V_1}{R_1 + \frac{R_2}{s} + j \cdot (X_1 + X_2)}$	$ I_2 = 22.178 \text{ A}$	$\arg(I_2) = -10.22 \text{ deg}$

$I_m := \frac{V_1}{j \cdot X_m}$	$ I_m = 8 \text{ A}$	$\arg(I_m) = -90 \text{ deg}$
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$I_1 := I_2 + I_m$	$ I_1 = 24.876 \text{ A}$	$\arg(I_1) = -28.671 \text{ deg}$
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$$P_{ag} := (|I_2|)^2 \cdot \frac{R_2}{s} \quad P_{ag} = 7.993 \text{ kW}$$

$$P_m := (|I_2|)^2 \cdot \frac{R_2}{s} \cdot (1 - s) \quad P_m = 7.673 \text{ kW}$$

$$P_{\text{rotational}} := 0.275 \text{ kW}$$

$$P_{\text{out}} := P_{\text{m}} - \frac{r_{\text{rotational}}}{3}$$

$$P_{\text{out}} = 7.581 \text{ kW}$$

$$P_{\text{in}} := |V_1| \cdot |I_1| \cdot \cos(\arg(I_1))$$

$$P_{\text{in}} = 8.73 \text{ kW}$$

$$\text{Efficiency, } \eta := \frac{P_{\text{out}}}{P_{\text{in}}} \cdot 100$$

$$\eta = 86.837$$

3 marks